

DAFTAR PUSTAKA

- [1] I. A. Darmanto, "Inovasi Sistem Robotika Pada Perpustakaan," *Journal of Electrical Engineering and Computer (JEECOM)*, vol. 2, no. 2, Art. no. 2, Oct. 2020, doi: 10.33650/jeecom.v2i2.1185.
- [2] S. Roni, "PENGEMBANGAN ROBOT PENDETEKSI OBYEK BERDASARKAN WARNA DENGAN SENSOR KAMERA SEBAGAI MEDIA PEMBELAJARAN."
- [3] C. Cheng, J. Fu, H. Su, and L. Ren, "Recent Advancements in Agriculture Robots: Benefits and Challenges," *Machines*, vol. 11, no. 1, Art. no. 1, Jan. 2023, doi: 10.3390/machines11010048.
- [4] M. Métillon, P. Cardou, K. Subrin, C. Charron, and S. Caro, "A Cable-Driven Parallel Robot With Full-Circle End-Effector Rotations," *Journal of Mechanisms and Robotics*, vol. 13, no. 3, p. 031017, Jun. 2021, doi: 10.1115/1.4049631.
- [5] T. Narayanan, R. S. Vishnu, R. R. Bhavani, and V. Vashista, "A cable driven parallel robot for coconut farm," in *2017 International Conference on Advances in Computing, Communications and Informatics (ICACCI)*, Sep. 2017, pp. 864–870. doi: 10.1109/ICACCI.2017.8125950.
- [6] T. P. Tho and N. T. Thinh, "An Overview of Cable-Driven Parallel Robots: Workspace, Tension Distribution, and Cable Sagging," *Mathematical Problems in Engineering*, vol. 2022, Jul. 2022, doi: 10.1155/2022/2199748.
- [7] R. C. Prayogo, A. Triwiyatno, and S. Sumardi, "PERANCANGAN ROBOT BERKAKI 4 (QUADRUPED) DENGAN STABILIZATION ALGORITHM PADA UNEVEN FLOOR MENGGUNAKAN 6-DOF IMU BERBASIS INVERS KINEMATIC," *Transient: Jurnal Ilmiah Teknik Elektro*, vol. 7, no. 2, Art. no. 2, Jun. 2018, doi: 10.14710/transient.v7i2.543-551.
- [8] M. Zarebidoki, J. S. Dhupia, and W. Xu, "A Review of Cable-Driven Parallel Robots: Typical Configurations, Analysis Techniques, and Control Methods," *IEEE Robotics & Automation Magazine*, vol. 29, no. 3, pp. 89–106, Sep. 2022, doi: 10.1109/MRA.2021.3138387.
- [9] Z. Zhang, Z. Shao, and L. Wang, "Optimization and implementation of a high-speed 3-DOFs translational cable-driven parallel robot," *Mechanism and Machine Theory*, vol. 145, p. 103693, Mar. 2020, doi: 10.1016/j.mechmachtheory.2019.103693.
- [10] T. P. Tho and N. T. Thinh, "Using a Cable-Driven Parallel Robot with Applications in 3D Concrete Printing," *Applied Sciences*, vol. 11, no. 2, Art. no. 2, Jan. 2021, doi: 10.3390/app11020563.
- [11] K. D. Hartomo, "IMPLEMENTASI METODE INTERPOLASI LINEAR UNTUK PEMBESARAN RESOLUSI CITRA," *Teknoin*, vol. 11, no. 3, Art. no. 3, 2006, doi: 10.20885/.v11i3.89.
- [12] I. Riadi, A. Fadlil, and P. Annisa, "Identifikasi Tulisan Tangan Huruf Katakana Jepang Dengan Metode Euclidean," *J-SAKTI (Jurnal Sains*

Komputer dan Informatika), vol. 4, no. 1, Art. no. 1, Mar. 2020, doi: 10.30645/j-sakti.v4i1.184.

- [13] A. Kviesis, V. Komasilovs, N. Ozols, and A. Zacepins, “Bee colony remote monitoring based on IoT using ESP-NOW protocol,” *PeerJ Comput. Sci.*, vol. 9, p. e1363, Apr. 2023, doi: 10.7717/peerj-cs.1363.